

# French Transportable Laser Ranging Station

## Chronometry accuracy estimation

M.Pierron - D.Feraudy - M.Furia - F.Pierron - OCA (Grasse)

Towards zero bias...



FTLRS in Chania (Creta)  
Gavdos campaign - 04 to 10 2003 -



laser maintenance



FTLRS in San Fernando (Spain)  
June 2004



### What conditions?

- ▶ Very short time intervals: (internal cal.  $< 30$  ns)
- ▶ External calibration: (100 m to 300 m)
- ▶ For satellites tracking: (400 km to 10 000 km)
- ▶ Time evolution (long-lasting effect)

### How?

With two timing systems:

- ▶ FTLRS Stanford chronometer (temperature controlled)
- ▶ Dassault Timers as a reference

**In same Context :**

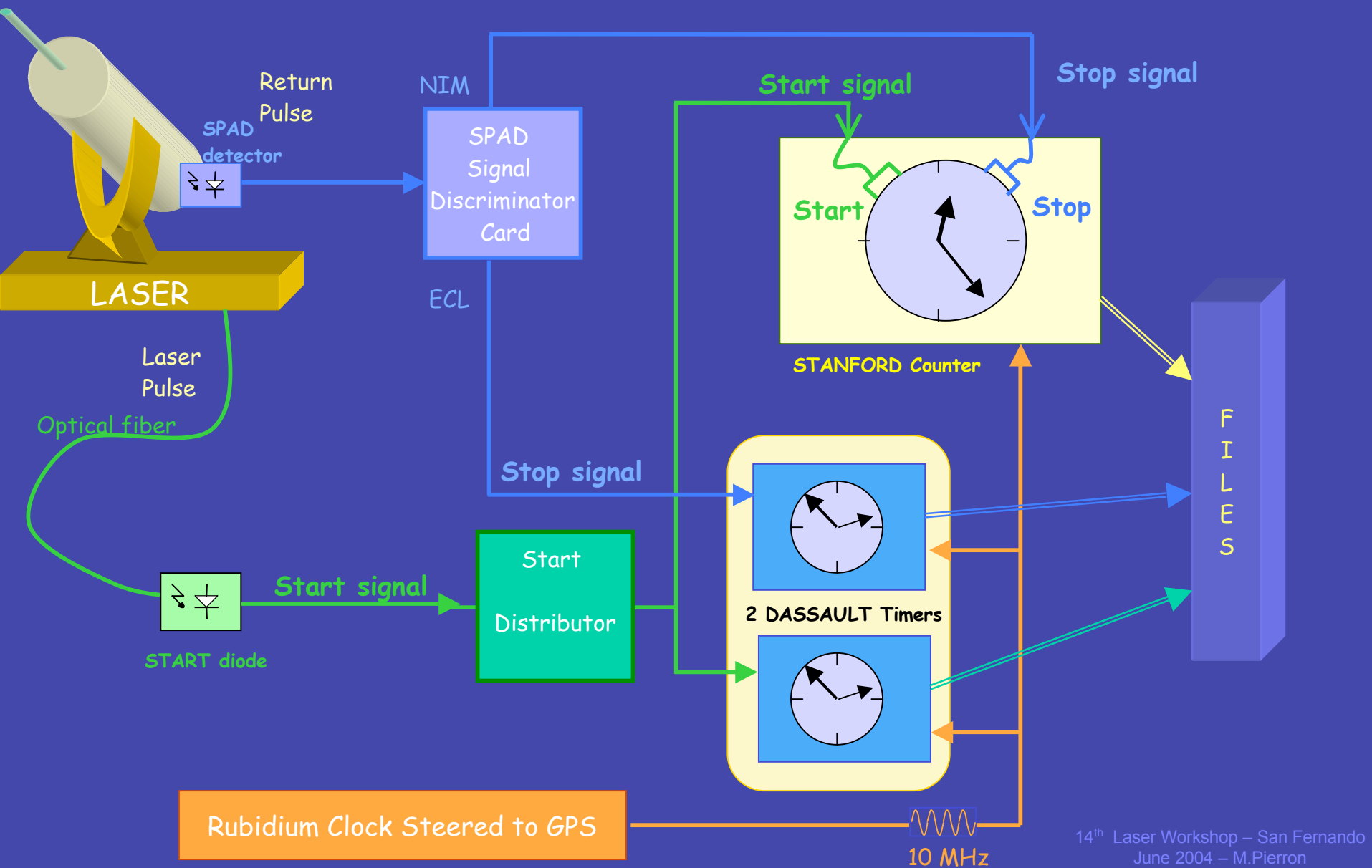
Laser for start

Photodiode for stop

Without mutual perturbation

**On same events :**

Echo or noise

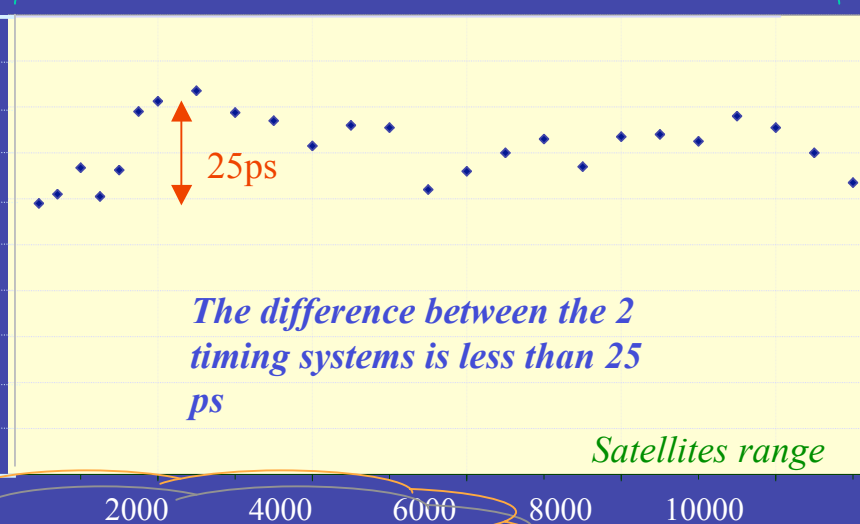
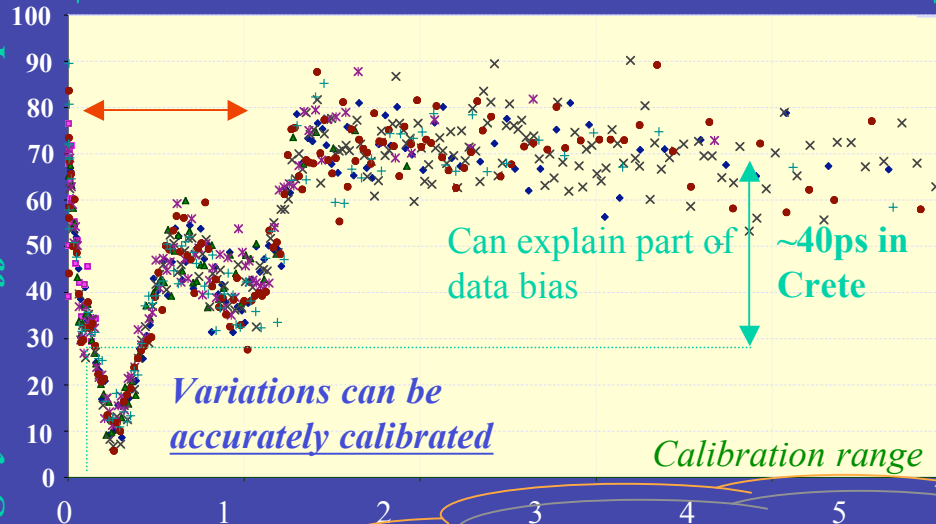


# Measurement results

0 to 5 km

400 to 10 000 km

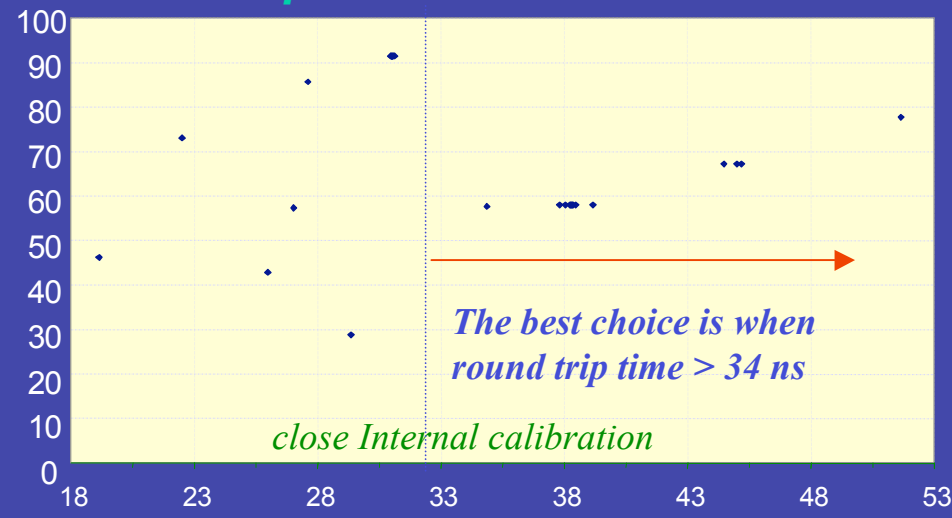
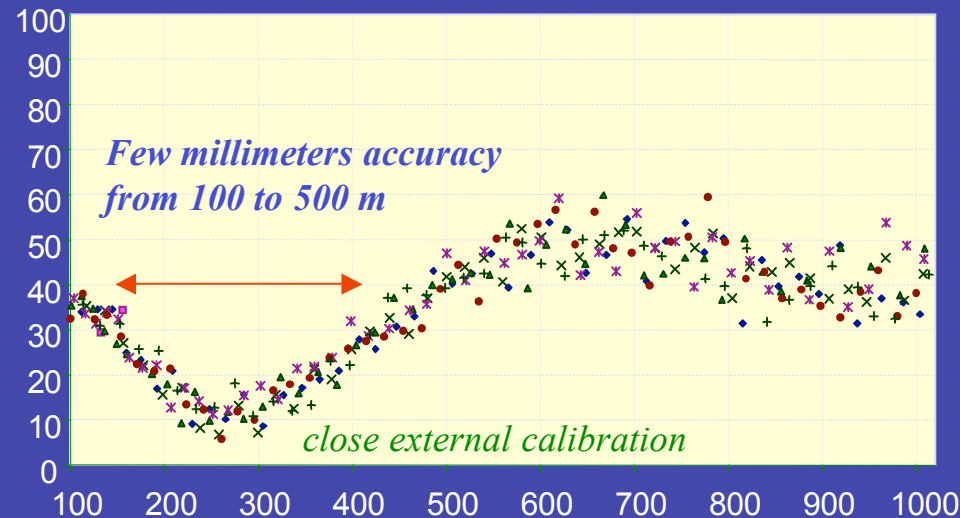
Timing systems difference in ps



All this measurements are NOT time dependant

From 100 meters to 1 km

Roundtrip time from 15 to 55 ns



# CONCLUSION

Very important to model the chronometry behavior at different ranges, and to process the calibration value accordingly.

- Stanford Chronometer can achieve *few millimeters accuracy during satellites tracking* (from 400 to 10 000 km).
- Range near external calibration is easy to model. *The correction to achieve for this external calibration can be tuned to 30/60 picos depending on the target's range.*
- Values near internal calibration range are more difficult to evaluate, except when the roundtrip time is longer than 34 nanos. *The difference between external and internal calibrations is about 50 picos (7.5 mm).*